



Calculus III Note-taking Guide Booklet

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¹ Herman, Edwin, Gilbert Strang, Joseph Lakey, Elaine A. Terry, Alfred K. Mulzet, Sheri J. Boyd, Joyati Debnath et al. "Calculus Volume 1." (2016).

² Herman, Edwin, Gilbert Strang, William Radulovich, Erica A. Rutter, David Smith, Kirsten R. Messer, Alfred K. Mulzet et al. "Calculus Volume 2." (2016).

³ Herman, Edwin, Gilbert Strang, Nicoleta Virginia Bila, Sheri J. Boyd, David Smith, Elaine A. Terry, David Torain et al. "Calculus Volume 3." (2016).

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1 4.8 L'Hôpital's Rule

Problem Set 1.1. *Find the following limits*

1.

$$\lim_{x \rightarrow 0} \frac{x^3}{x} =$$

2.

$$\lim_{x \rightarrow 0} \frac{x}{x^3} =$$

3.

$$\lim_{x \rightarrow 0} \frac{x}{x} =$$

4.

$$\lim_{x \rightarrow 0} \frac{x + x^3}{2} =$$

5.

$$\lim_{x \rightarrow 0} \frac{x}{x + 4x^2} =$$

Theorem 1.2. *L'Hôpital's Rule*

Problem Set 1.3. Evaluate the following limits.

1.

$$\lim_{x \rightarrow 0} \frac{\sin(x)}{x} =$$

2.

$$\lim_{x \rightarrow 0} \frac{e^{1/x} - 1}{e^{1/x}} =$$

3.

$$\lim_{x \rightarrow 0} \frac{\sin x - x}{x^2} =$$

Other Indeterminant Forms

•

•

•

Example 1.4.

$$\lim_{x \rightarrow 0^+} \frac{1}{x^2} - \frac{1}{\tan(x)}$$

Indeterminant Powers

If $\lim_{x \rightarrow a} \ln(f(x)) = L$, then

Example 1.5. *Evaluate*

$$\lim_{x \rightarrow \infty} x^{\frac{1}{x}}$$

.

2 3.7 Improper Integrals

Definition 2.1. *Integrating over an Infinite Interval*

1. *If $f(x)$ is continuous on $[a, \infty)$, then*

2. *If $f(x)$ is continuous on $(-\infty, b]$, then*

3. *If $f(x)$ is continuous on $(-\infty, \infty)$, then*

In each cases, if the limit exists, then the improper integral is said to _____. Otherwise, if the limit does not exist, then the improper integral is said to _____.

Example 2.2. We evaluate

$$\int_1^{\infty} \frac{1}{x} dx =$$

Problem Set 2.3. Evaluate

$$\int_{-\infty}^0 \frac{1}{x^2 + 4} dx$$

Definition 2.4. *Integrating a Discontinuous Integrand*

1. If $f(x)$ is continuous on $[a, b)$, then

2. If $f(x)$ is continuous on $(a, b]$, then

3. If $f(x)$ is continuous on $[a, b]$ except at c in (a, b) , then

In each case, if the limit exists and is finite, then the improper integral is said to _____.
Otherwise, the improper integral is said to _____.

Example 2.5. We evaluate

$$\int_{-1}^1 \frac{1}{x^3} dx =$$

Theorem 2.6. The Direct Comparison Test Let f, g be continuous on $[a, \infty)$ and assume that $0 \leq f(x) \leq g(x)$ for all $x \geq a$. Then

1. If $\int_a^\infty g(x) dx$ _____, then $\int_a^\infty f(x) dx$ also _____.
2. If $\int_a^\infty f(x) dx$ _____, then $\int_a^\infty g(x) dx$ also _____.

Example 2.7. Consider for $p < 1$

$$\int_1^\infty (x+7)^p dx$$

3 5.1 Sequences

Definition 3.1. An _____ is an ordered list a of numbers of the form

Each of the numbers is called a _____. The symbol n is called the _____ for the sequence.

We also use the notation

Example 3.2. *Examples of sequences:*

We sometimes would like to write sequences using its _____.

Problem Set 3.3. *Write each sequences given using its explicit formula. We will do the second one together:*

- 1, 2, 3, 4, ...

- 2, 4, 6, 8, 10

- 1, -1, 1, -1, ...

- 1, 1, 2, 3, 5, 8, ...

3.1 Limit of a Sequence

Definition 3.4. *Given a sequence $\{a_n\}$, if the terms of a_n become _____ to a _____ as _____, we say $\{a_n\}$ is a _____ and L is the _____. In this case, we write*

If a sequence is not convergent, we say it is _____.

More formally, we can instead use the definition:

Definition 3.5. *A sequence $\{a_n\}$ _____ to the number _____ if for every $\varepsilon > 0$ there corresponds an integer N such that if $n \geq N$,*

The number L is the _____ and we write

Example 3.6. Let $\{a_n\} = \{\frac{1}{n}\}$ and $\{b_n\} = \{(-1)^n\}$. We investigate the convergence or divergence of each.

3.2 Calculating Limits of Sequences

Theorem 3.7. Limit of a Sequence Defined by a function Consider a sequence $\{a_n\}$ such that $a_n = f(n)$. If
_____ such that

then $\{a_n\}$ converges and

Theorem 3.8. Algebraic Limit Laws: Given sequences $\{a_n\}$ and $\{b_n\}$ and a real number C , if there exist constants A, B such that $\lim_{n \rightarrow \infty} a_n = A, \lim_{n \rightarrow \infty} b_n = B$. Then

1.

2.

3.

4.

5.

Theorem 3.9. Consider a sequence $\{a_n\}$ and suppose there exists a real number L such that the sequence $\{a_n\}$ converges to L . Suppose f is a continuous function at L . Then there exists an integer N such that f is defined at all values a_n for $n \geq N$, and the sequence

This allows us to use things like L'Hôpital's rule for sequences.

Theorem 3.10. The Squeeze Theorem for Sequences Consider sequences $\{a_n\}, \{b_n\}, \{c_n\}$ and suppose that _____ for all $n \geq N$ for some N . If

then

Problem Set 3.11. If possible, find the limits of the following sequences.

1. $1, 2, 3, 4, \dots$

2. $5, 19, 5, 19, 5, 19, \dots$

3. $\{\frac{1}{n^2}\}$

3.3 Bounded and Monotonic Sequences

Definition 3.12. A sequence $\{a_n\}$ is _____ if there exists a number M so that _____ for all n .

A sequence $\{a_n\}$ is _____ if there exists a number m so that _____ for all n .

A sequence $\{a_n\}$ is a _____ if it is bounded above and bounded below.

If a sequence is not bounded, it is an _____

Definition 3.13. A sequence $\{a_n\}$ is _____ if _____ for all n . It is _____ if _____ for all n . A sequence is _____ if it is either _____ or _____

Theorem 3.14. Montone Convergence Theorem If $\{a_n\}$ is a _____ sequence and there exists a positive integer n_0 such that $\{a_n\}$ is _____ for all $n \geq n_0$, then $\{a_n\}$ _____

Problem Set 3.15. Classify each sequence as bounded or not and monotonic or not. Then using that information, decide if we know if the sequence converges.

1. $1, 2, 3, 4, \dots$

2. $5, 19, 5, 19, 5, 19, \dots$

3. $\{(-1)^n\}$

4. $\{\frac{1}{n}\}$

5. $a_n = a_1$, where $a_1 = 7$

4 5.2 Infinite Series

Definition 4.1. An _____ is a sum of infinitely many terms and is written in the form

For each k , S_k is _____

If we can describe the convergence of a series to S , we call S the _____, and we write

If the sequence of partial sums diverges, we have the _____

Example 4.2. Decide whether each sum converges or diverges.

•

$$\sum_{n=1}^{\infty} 1$$

•

$$\sum_{n=1}^{\infty} 0$$

Example 4.3. Find the sum of the *telescoping series*

$$\sum_{n=1}^{\infty} \frac{1}{n(n+1)}$$

Theorem 4.4. Let $\sum a_n, \sum b_n$ be convergent series. Then we have:

1. *Sum/Difference Rule:*
2. *Constant Multiple Rule:*

4.1 Geometric Series

Definition 4.5. A _____ is any series that we can write in the form

where a, r are fixed and $a \neq 0$.

Problem Set 4.6. Identify if each is a geometric series. If it is, what are a, r ?

1. $1 + \frac{1}{2} + \frac{1}{4} + \dots + \left(\frac{1}{2}\right)^{n-1} + \dots$

2. $2 - \frac{2}{3} + \frac{2}{9} - \frac{2}{27} + \dots$

3. $1 + \frac{1}{2} + \frac{1}{3} + \frac{1}{4} + \frac{1}{5} + \dots$

4. $5 + 5 + 5 + 5 + \dots$

4.1.1 Convergence of the Geometric Series

Goal: Write S_n in terms of a, r . This way we know what the partial sum is of any geometric series. Consider

$$S_n = a + ar + \dots + ar^{n-1}$$

Theorem 4.7. If _____ in a geometric series, then

If _____ in a geometric series, then it _____.

Problem Set 4.8. Decide whether each geometric series converges or diverges. If it converges, what is its sum?

1. $1 + \frac{1}{2} + \frac{1}{4} + \dots + \left(\frac{1}{2}\right)^{n-1} + \dots$

2. $2 - \frac{2}{3} + \frac{2}{9} - \frac{2}{27} + \dots$

3. $5 + 5 + 5 + 5 + \dots$

5 5.3 The Divergence and Integral Tests

Theorem 5.1. Divergence Test If $\lim_{n \rightarrow \infty} a_n = c \neq 0$ or does not exist, then $\sum_{n=1}^{\infty} a_n$ _____.

Example 5.2. Consider

$$\sum_{n=1}^{\infty} \frac{1}{n}, \int_1^{\infty} \frac{1}{x} dx.$$

Let $f(x) = \frac{1}{x}$. Then

Theorem 5.3. Integral Test Suppose $\sum_{n=1}^{\infty} a_n$ is a series with positive terms. Suppose there exists a function f and a positive integer N such that the following three conditions are satisfied:

- 1.
- 2.
- 3.

Then

both _____ or both _____.

Problem Set 5.4. Use the integral test to decide whether each series converges or diverges.

1. $\sum_{n=1}^{\infty} \frac{1}{n^p}, p > 1$

Definition 5.5. For any real number p , the series

is called a _____.

6 5.4 Comparison Tests

Theorem 6.1. 1. Suppose there exists an integer N such that $0 \leq a_n \leq b_n$ for all $n \geq N$. If _____
then _____

2. Suppose there exists an integer N such that $a_n \geq b_n \geq 0$ for all $n \geq N$. If _____,
then _____

Example 6.2. We investigate the convergence or lack thereof of $\sum \frac{1}{n^3+3n+1}$.

Problem Set 6.3. Investigate the convergence or lack thereof of $\sum \frac{1}{2^n-1}$.

Theorem 6.4. Limit Comparison Test Let $a_n, b_n > 0$ for all $n \geq 1$.

1.

2.

3.

Example 6.5. We use LCT to determine the convergence or divergence of $\sum_{n=1}^{\infty} \frac{\ln(n)}{n^2}$.

Problem Set 6.6. Using LCT, determine whether or not each series converges or diverges.

1. $\sum \frac{2n+1}{n^2+2n+1}$

2. $\sum \frac{5^n}{3^{n+2}}$

7 5.5 Alternating Series

Definition 7.1. Any series whose terms alternate between positive and negative values is called an _____. An _____ can be written in the form

Theorem 7.2. Alternating Series Test An alternating series converges if

1.

2.

Example 7.3. Consider

$$\sum_{n=1}^{\infty} (-1)^{n+1} \frac{1}{n}.$$

Theorem 7.4. Remainders in Alternating Series Consider an alternating series that satisfies the hypotheses of the alternating series test. Let S denote the sum of the series and S_N denote the N th partial sum. For any integer $N \geq 1$, the remainder _____ satisfies

Definition 7.5. A series $\sum a_n$ exhibits _____ if _____. A series $\sum a_n$ exhibits _____ if _____, but _____.

Problem Set 7.6. Decide whether or not $\sum \frac{\cos(n\pi)}{n^2}$ and $\sum \frac{\cos(n\pi)}{n}$ are alternating series and whether they converge or diverge. If they converge, does they converge absolutely or conditionally?

8 5.6 Ratio and Root Tests

Theorem 8.1. Ratio Test Let $\sum a_n$ be any series be a series with nonzero terms. Let

1. If _____, then _____
2. If _____, then _____
3. If _____, then _____

Note: This extends the knowledge we already had for geometric series.

Theorem 8.2. Root Test Consider the series $\sum a_n$. Let

1. If _____, then _____
2. If _____, then _____
3. If _____, then _____

Problem Set 8.3. Determine if the following series converge absolutely.

1. $\sum \frac{2^n}{n!}$

2. $\sum \frac{(-1)^n (n!)^2}{(2n)!}$

3. $\sum \left(\frac{1}{n}\right)^n$

9 6.1 Power Series and Functions

Definition 9.1. A series of the form

is a _____ . A series of the form

is a _____ .

Example 9.2.

$$\sum_{n=0}^{\infty} x^n$$

Theorem 9.3. Convergence of a Power Series Consider the power series $\sum_{n=0}^{\infty} c_n(x-a)^n$. The series satisfies exactly one of the following properties:

1.

2.

3.

Definition 9.4. Consider the power series $\sum_{n=0}^{\infty} c_n(x-a)^n$. The set of real numbers x where the series converges is the _____ . If there exists a real number $R > 0$ such that the series _____ and _____, then R is the _____ . If the series converges only at $x = a$, we say the radius of convergence is _____. If the series converges for all real numbers x , we say the radius of convergence is _____.

How to Test a Power Series for Convergence

1. Use the _____ to find the largest open interval where the series converges

- 2.

- 3.

Example 9.5. Determine where the Power Series $\sum (-1)^{n-1} \frac{x^n}{n}$ converges or diverges.

Problem Set 9.6. Determine where the power series below converge or diverge.

1. $\sum \frac{x^n}{n!}$

2. $\sum n!x^n$

10 6.2 Properties of Power Series

Theorem 10.1. Combining Power Series Suppose that the two power series $\sum_{n=0}^{\infty} c_n x^n$ and $\sum_{n=0}^{\infty} d_n x^n$ converge to the functions f and g , respectively, on a common interval I .

1.

2.

3.

Theorem 10.2. Suppose that the power series $\sum_{n=0}^{\infty} c_n x^n$ and $\sum_{n=0}^{\infty} d_n x^n$ converge to f and g , respectively, on a common interval I . Let

Then

and

Theorem 10.3. Term-by-Term Differentiation and Integration of Power Series Suppose that the power series $\sum_{n=0}^{\infty} c_n x^n$ converges on the interval $(a - R, a + R)$ for some $R > 0$. Let f be the function defined by the series

Then f is _____ on the interval $(a - R, a + R)$ and we can find f' by differentiating the series term-by-term:

for $|x - a| < R$. Also, to find _____, we can integrate the series term-by-term. The resulting series converges on $(a - R, a + R)$, and we have

for $|x - a| < R$.

Warning! This may not work for series that are not Power Series.

Example 10.4. *Let*

$$f(x) = \sum_0^{\infty} \frac{(-1)^n x^{2n+1}}{2n+1}, \quad -1 \leq x \leq 1$$

We identify this as a function we more commonly know.

11 6.3 Taylor and Maclaurin Series

Definition 11.1. *If f has derivatives of all orders at $x = a$, then the _____
is*

The Taylor series for f at _____ is known as the _____

Definition 11.2. *If f has n derivatives at $x = a$, then the n th _____ for f at a is*

Example 11.3. *We find the Taylor series generated by $1/x^2$ at $a = 1$.*

Problem Set 11.4. Find the Taylor Series generated by $f(x) = x^3$ at $x = 3$.

Example 11.5. We find the Taylor Polynomial of degree n of e^x .

Theorem 11.6. Taylor's Theorem with Remainder Let f be a function that can be differentiated $n + 1$ times on an interval I containing the real number a . Let p_n be the n th Taylor polynomial of f at a and let

be the _____. Then for each x in the interval I , there exists a real number c between a and x such that

If there exists a real number M such that _____ for all $x \in I$, then

for all x in I .

Example 11.7. We find the Taylor Series of $\sin(x)$.

12 6.4 Working with Taylor Series

Note: We can use the following from here on without proof

$$e^x =$$
$$\cos(x) =$$
$$\sin(x) =$$

Example 12.1. We express $\int e^{-x^2} dx$ as an infinite series.

Problem Set 12.2. Find the Taylor Series for $\sinh(x)$. *Hint:* Recall $\sinh(x) = \frac{e^x - e^{-x}}{2}$.

13 7.1 Parametric Equations

Definition 13.1. If x and y are continuous functions of t on an interval I , then the equations

are called _____ and _____ is called the _____.
The set of points (x, y) obtained as t varies over the interval I is called the _____.
The graph of parametric equations is called a _____ or plane curve, and is denoted by C .

Example 13.2. Consider $x = \sin \frac{\pi t}{2}, y = 2t + 4, 0 \leq t \leq 4$.

Problem Set 13.3. Sketch the curve

$$x = 3t + 2, y = t^2 + 1, -\infty < t < \infty.$$

Example 13.4. We find two different parametric equations to represent the graph of $y = 2x^2 + 3$.

13.1 Cycloids

Example 13.5. A wheel of radius a rolls along a horizontal straight line. We find parametric equations for the path traced by a point on the wheel. The path is called a _____.

14 7.2 Calculus of Parametric Curves

14.1 Derivatives of Parametric Equations

Parametric Formula for $\frac{dy}{dx}$

Parametric Formula for $\frac{d^2y}{dx^2}$

Example 14.1. Find the tangent line to the plane curve defined by the parametric equations

$$x(t) = t^2 - 3, \quad y(t) = 2t - 1, \quad t \geq 0$$

at $t = 0$.

Problem Set 14.2. Find $\frac{d^2y}{dx^2}$ as a function of t if $x = 1 - t^2$, $y = t - t^2$.

Example 14.3. We set up, but do not evaluate, an integral that gives the area under the curve of the cycloid defined by the equations

$$x = t - \sin(t), \quad y = 1 - \cos(t), \quad 0 \leq t \leq 2\pi.$$

Definition 14.4. Consider the plane curve defined by the differentiable parametric equations $x = x(t)$, $y = y(t)$, $t_1 \leq t \leq t_2$. Then the _____ is given by

$$L =$$

Problem Set 14.5. Find the length of the circle of radius r defined parametrically by

$$x = r \cos t, \quad y = r \sin t, \quad 0 \leq t \leq 2\pi.$$

Areas of Surface of Revolution for Parametrized Curves

1. Revolution about the x -axis:

2. Revolution about the y -axis:

15 7.3 Polar Coordinates

Definition 15.1. The point P has Cartesian coordinates (x, y) . The line segment connecting the origin to the point P measures the distance from the origin to P and has _____ . The _____ .

This is the basis of the _____ . In the _____ , each point also has two values associated with it: _____ .

Example 15.2. We find all of the polar coordinates for the point $P(2, \pi/6)$.

Theorem 15.3. Converting Points between Coordinate Systems: Given a point P in the plane with _____ and _____ the following conversion formulas hold true:

Some curves are easier to express in polar and some are easier to express in Cartesian.

Example 15.4. *We find the polar equation for the circle $x^2 + (y - 3)^2 = 3^2$ (circle centered at $(0,3)$ with radius 3).*

15.1 Polar Curves

Example 15.5. *We graph $r = 4 \sin \theta$.*

Problem Set 15.6. *Graph the curve $r = 1 - \cos(\theta)$.*

Example 15.7. *Polar objects can have multiple representations*

-

-

Problem Set 15.8. Graph the sets of points using the conditions:

- $1 \leq r \leq 3$ and $0 \leq \theta \leq \pi/2$

- $-3 \leq r \leq 2$ and $\theta = \pi/4$

- $2\pi/3 \leq \theta \leq 5\pi/6$

15.2 Transforming Polar Equations to Rectangular Coordinates

Problem Set 15.9. Write the polar equation as a Cartesian equation.

- $r \cos(\theta) = 2$

- $r = 6 \cos \theta - 8 \sin \theta$

- $r = 1 - \cos(\theta)$

16 7.4 Area and Arc Length in Polar Coordinates

16.1 Slope of Polar Curves

Recall: Slope of a curve in Cartesian is $\frac{dy}{dx}$. This is **not** true in polar. When $r = f(\theta)$:

Areas of Regions Bounded by Polar Curves

Theorem 16.1. Suppose f is continuous and nonnegative on the interval $\alpha \leq \theta \leq \beta$ with _____.
The area of the region bounded by the graph of _____ between the radial lines $\theta = \alpha$ and $\theta = \beta$ is

Problem Set 16.2. Find the area of the region enclosed by $r = 1 - \cos \theta$.

Example 16.3. We find the area of the region that lies outside the cardioid $r = 2 + 2 \sin \theta$ and inside the circle $r = 6 \sin \theta$.

16.2 Arc Length in Polar Coordinates

Theorem 16.4. Let f be a function whose derivative is continuous on an interval $\alpha \leq \theta \leq \beta$. The length of the graph of $r = f(\theta)$ from $\theta = \alpha$ to $\theta = \beta$ is

Problem Set 16.5. Find the arc length of the $r = 2 + 2 \cos \theta$.

17 2.1 Vectors in the Plane

Definition 17.1. A _____ is a quantity that has both _____ and _____.

Definition 17.2. Vectors are said to be _____ vectors if they have the _____.

Definition 17.3. The vector with initial point $(0, 0)$ and terminal point (x, y) can be written in component form as

The scalars x and y are called the _____ of \mathbf{v} .

Example 17.4. Consider $\mathbf{v} = \overrightarrow{PQ}$ with $P(-3, 4)$ and $Q(-5, 2)$. The vector \mathbf{v} has components

-
-

So the component form is _____. The length is

17.1 Combining Vectors

Definition 17.5. Let k be a **scalar** (a real number). Then if \mathbf{u}, \mathbf{v} are vectors then we have

- Addition/Subtraction:
- Scalar Multiplication:

Problem Set 17.6. If $\mathbf{u} = \langle -1, 3 \rangle$ and $\mathbf{v} = \langle 4, 7 \rangle$ find:

- $2\mathbf{u} - 3\mathbf{v}$
- $\|\frac{1}{2}\mathbf{u}\|$

- $\frac{1}{2}\|\mathbf{u}\|$

Properties of Vector Operations

1. $\mathbf{u} + \mathbf{v} =$
2. $\mathbf{u} + \mathbf{0} =$
3. $0\mathbf{u} =$
4. $a(b\mathbf{u}) =$
5. $(a + b)\mathbf{u} =$
6. $(\mathbf{u} + \mathbf{v}) + \mathbf{w} =$
7. $\mathbf{u} - \mathbf{u} =$
8. $1\mathbf{u} =$
9. $a(\mathbf{u} + \mathbf{v}) =$

17.2 Unit Vectors

Definition 17.7. A _____ is a vector with _____.
 For any nonzero vector \mathbf{v} , we can use scalar multiplication to find a unit vector \mathbf{u} that has the same direction as \mathbf{v} .

Problem Set 17.8. Find a unit vector \mathbf{u} in the direction of the vector from $P_1(1, 0)$ and $P_2(3, 2)$.

18 2.2 Vectors in Three Dimensions

Definition 18.1. The _____ rectangular coordinate system consists of three perpendicular axes: the x -axis, the y -axis, _____, and an origin at the point of intersection of the axes.

Theorem 18.2. The _____ between points _____ and _____ is given by the formula

Definition 18.3. A _____ is the set of all points in space _____ from a fixed point, the _____ of the sphere. In a sphere, the distance from the center to a point on the sphere is called the _____.

The sphere with center (a, b, c) and radius r can be represented by the equation

18.1 Graphing Other Equations in Three Dimensions

Example 18.4. We describe the set of points in three-dimensional space that satisfies $(x - 2)^2 + (y - 1)^2 = 4$, and graph the set.

18.2 Working with Vectors in 3D

Example 18.5. Let \vec{PQ} be the vector with initial point $P = (3, 12, 6)$ and terminal point $Q = (-4, -3, 2)$. We express \vec{PQ} in both component form and using standard unit vectors.

Problem Set 18.6. If $\mathbf{u} = \langle -1, 3, 0 \rangle$ and $\mathbf{v} = \langle 4, 7, 11 \rangle$ find:

- $2\mathbf{u} - 3\mathbf{v}$

- $\|\frac{1}{2}\mathbf{u}\|$

- $\frac{1}{2}\|\mathbf{u}\|$

19 2.3 The Dot Product

Definition 19.1. The _____ of two vectors is $\mathbf{u} = \langle u_1, u_2, u_3 \rangle$ and $\mathbf{v} = \langle v_1, v_2, v_3 \rangle$

Theorem 19.2. The _____ of two vectors is the product of the _____ of each vector and the _____ of the angle between them.

Problem Set 19.3. 1. Find the dot product of $\mathbf{u} = \langle 1, -2, -2 \rangle$ and $\mathbf{v} = \langle -6, 2, -3 \rangle$.

2. Find the angle between $\mathbf{u} = \mathbf{i} - 2\mathbf{j} - 2\mathbf{k}$ and $\mathbf{v} = 6\mathbf{i} + 3\mathbf{j} + 0\mathbf{k}$.

Theorem 19.4. The nonzero vectors \mathbf{u} and \mathbf{v} are _____ if and only if _____.

Properties of the Dot Product

1. $\mathbf{u} \cdot \mathbf{v} =$

2. $c\mathbf{u} \cdot \mathbf{v} =$

3. $\mathbf{u} \cdot (\mathbf{v} + \mathbf{w}) =$

4. $\mathbf{u} \cdot \mathbf{u} =$

5. $\mathbf{0} \cdot \mathbf{u} =$

19.1 Vector Projections

The _____ is the vector labeled _____. It has the same _____ as \mathbf{u} and \mathbf{v} and the same _____, and represents the _____ that acts in the _____. If θ represents the angle between \mathbf{u} and \mathbf{v} , then the length of $proj_{\mathbf{u}}\mathbf{v}$ is _____. When expressing $\cos \theta$ in terms of the dot product, this becomes

We now multiply by a unit vector in the direction of \mathbf{u} to get $proj_{\mathbf{u}}\mathbf{v}$

The length of this vector is also known as the _____ and is denoted by

Problem Set 19.5. Find the vector projection of $\mathbf{u} = 6\mathbf{i} + 3\mathbf{j} + 2\mathbf{k}$ onto $\mathbf{v} = \mathbf{i} - 0\mathbf{j} - 0\mathbf{k}$.

20 2.4 The Cross Product

Definition 20.1. *The **cross product** of two vectors is*

where \mathbf{n} is the _____.

Parallel Vectors Nonzero vectors \mathbf{u}, \mathbf{v} are _____ if and only if _____.

Properties of the Cross Product If $\mathbf{u}, \mathbf{v}, \mathbf{w}$ are vectors and r, s are scalars, then

1. $r(\mathbf{u}) \times (s\mathbf{v}) =$

2. $\mathbf{u} \times (\mathbf{v} + \mathbf{w}) =$

3. $\mathbf{v} \times \mathbf{u} =$

4. $(\mathbf{v} + \mathbf{w}) \times \mathbf{u} =$

5. $\mathbf{0} \times \mathbf{u} =$

6. $\mathbf{u} \times (\mathbf{v} \times \mathbf{w}) =$

Example 20.2. *Area of a Parallelogram*

Example 20.3. *We find the cross product of the three dimensional vectors $\mathbf{u} = 2\mathbf{i} + \mathbf{j} + \mathbf{k}$ and $\mathbf{v} = -4\mathbf{i} + 3\mathbf{j} + \mathbf{k}$.*

Problem Set 20.4. *Find the cross product of the three dimensional vectors $\mathbf{u} = \mathbf{i}$ and $\mathbf{v} = \mathbf{j}$.*

21 2.5 Equations of Lines and Planes in Space

Recall:

- Slope-intercept form of a line: $y = mx + b$
- A parametric form of a line: $x(t) = m_1t + x_0$, $y(t) = m_2t + b$, $-\infty < t < \infty$

Definition 21.1. A _____ parallel to vector _____ and passing through point _____ can be described by the following parametric equations:

If the constants a, b , and c are all nonzero, then L can be described by the symmetric equation of the line:

Problem Set 21.2. Find parametric and symmetric equations of the line passing through points $(1, 0, -2)$ and $(-3, 5, 0)$.

Example 21.3. A mouse travels from its home (the origin) to a piece of cheese in the direction of the point $(1, 1, 1)$ at a speed of 60 cm per second. What is its position after 10 seconds?

21.1 Distance between a Point and a Line

21.2 Equations for a Plane

Definition 21.4. Given a point P and vector \mathbf{n} , the set of all points Q satisfying the equation _____ forms a _____. The equation

is known as the _____.

The _____ containing point $P = (x_0, y_0, z_0)$ with normal vector $\mathbf{n} = \langle a, b, c \rangle$ is

This equation can be expressed as _____ where _____.

This form of the equation is sometimes called the _____.

Problem Set 21.5. Find an equation for the plane through $P_0(-3, 0, 7)$ perpendicular to

$$\mathbf{n} = 2\mathbf{j} - \mathbf{k}.$$

Example 21.6. We find an equation for the plane through $A(0, 0, 1)$, $B(2, 0, 0)$, and $C(0, 3, 0)$.

Problem Set 21.7. Find a vector parallel to the line of intersection of the planes $3x - 6y - 2z = 15$ and $2x + y - 2z = 5$.
Hint: This line of intersection is perpendicular to both planes normal vectors.

Example 21.8. We find the point where the line

$$x(t) = \frac{8}{3} + 2t, \quad y(t) = -2t, \quad z(t) = 1 + t$$

intersects the plane $3x + 2y + 6z = 6$.

22 3.1 Vector-Valued Functions and Space Curves

Definition 22.1. A _____ is a function of the form

where the _____ f, g, h , are real-valued functions of the parameter t . Vector-valued functions are also written in the form

Example 22.2. We sketch $\mathbf{r}(t) = \cos(t)\mathbf{i} + \sin(t)\mathbf{j} + t\mathbf{k}$.

Problem Set 22.3. Describe how the following compare to $\mathbf{r}(t) = \cos(t)\mathbf{i} + \sin(t)\mathbf{j} + t\mathbf{k}$.

- $\mathbf{r}(t) = \cos(2t)\mathbf{i} + \sin(2t)\mathbf{j} + t\mathbf{k}$.
- $\mathbf{r}(t) = \cos(t)\mathbf{i} + \sin(t)\mathbf{j} + 2t\mathbf{k}$.

Definition 22.4. A vector-valued function r approaches the _____ as t approaches a , written

provided

Theorem 22.5. Let f , g , and h be functions of t . Then the limit of the vector-valued function $\mathbf{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$ as t approaches a is given by

provided the limits exist.

Problem Set 22.6. Let $\mathbf{r}(t) = \frac{2t-4}{t+1}\mathbf{i} + \frac{t}{t^2+1}\mathbf{j} + (4t-3)\mathbf{k}$. Find $\lim_{t \rightarrow 3} \mathbf{r}(t)$.

Definition 22.7. Let f, g, h functions of t . Then, the vector-valued function $\mathbf{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$ is _____ if the following three conditions hold:

-
-
-

23 3.2 Calculus of Vector-Valued Functions

Theorem 23.1. Let f, g, h be differentiable functions of t and let $\mathbf{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$. Then

Problem Set 23.2. Let $\mathbf{r}(t) = t \ln(t)\mathbf{i} + 5e^t\mathbf{j} + \cos(t)\mathbf{k}$. Find $\mathbf{r}'(t)$ and $\mathbf{r}''(t)$.

23.1 Tangent Vectors and Unit Tangent Vectors

Definition 23.3. Let C be a curve defined by a vector-valued function \mathbf{r} , and assume that $\mathbf{r}'(t)$ exists when $t = t_0$. A _____ \mathbf{v} at $t = t_0$ is any vector such that, when the tail of the vector is placed at point $\mathbf{r}(t_0)$ on the graph, vector \mathbf{v} is _____ to curve C . Vector _____ is an example of a tangent vector at point $t = t_0$. The _____ at t is defined to be

Problem Set 23.4. Find the a tangent vector and the unit tangent vector for each of $\mathbf{r}(t) = \cos(t)\mathbf{i} + \sin(t)\mathbf{j}$.

23.2 Integrals of Vector-Valued Functions

Definition 23.5. The _____ of a vector-valued function $\mathbf{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$ is

The _____ of the vector-valued function is

Problem Set 23.6. Calculate $\int_1^3 ((2t + 4)\mathbf{i} - t^2\mathbf{j}) dt$.

24 3.3 Arc Length and Curvature

Recall: Arc Length of a Parametric Curve

Theorem 24.1. Given a smooth curve C defined by the function $\mathbf{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$, where t lies within the interval $[a, b]$, the _____ of C over the interval is

Problem Set 24.2. Calculate the arc length for $\mathbf{r}(t) = \sin(t)\mathbf{i} + \cos(t)\mathbf{j} + (10 - t)\mathbf{k}$, from $t = 0$ to $t = 2\pi$.

Theorem 24.3. Let $\mathbf{r}(t)$ describe a smooth curve for $t \geq a$. Then the arc-length function is given by

Furthermore, _____.

24.1 Curvature

Definition 24.4. Let C be a smooth curve in the plane or in space given by $\mathbf{r}(s)$, where s is the arc-length parameter. The _____ is

Theorem 24.5. If C is a smooth curve given by $\mathbf{r}(t)$, then the curvature κ of C at t is given by

or

If C is the graph of a function $y = f(x)$ and both y' and y'' exist, then the curvature at point (x, y) is given by

We show the first formula:

Problem Set 24.6. Find the curvature for each of the following curves at the given point:

$$\mathbf{r}(t) = 4 \cos t \mathbf{i} + 4 \sin t \mathbf{j} + 3t \mathbf{k}, t = 4\pi/3$$

24.2 The Normal and Binormal Vectors

Definition 24.7. Let C be a three-dimensional smooth curve represented by \mathbf{r} over an open interval I . If $\mathbf{T}(t) \neq 0$, then the _____ is

The _____ is

where $\mathbf{T}(t)$ is the unit tangent vector.

Note:

Problem Set 24.8. Find the principal unit normal vector and the binormal vector for $\mathbf{r}(t) = 4 \cos t\mathbf{i} + 4 \sin t\mathbf{j} + 3t\mathbf{k}$.

Definition 24.9. Suppose we form a circle in the osculating plane of C at point P on the curve. Assume that the circle has the _____ as the curve does at point P and let the circle have _____. Then, the _____ is given by _____.

We call _____ of the curve, and it is equal to the reciprocal of the curvature. If this circle lies on the _____ side of the curve and is _____ at point P , then this circle is called the _____.

Example 24.10. Find the equation of the osculating circle of the curve defined by the vector-valued function $y = x^2$ at the origin.

25 3.4 Motion in Space

Definition 25.1. Let $\mathbf{r}(t)$ be a twice-differentiable vector-valued function of the parameter t that represents the _____ of an object as a function of time. The _____ is

The _____ is

The _____ is

Problem Set 25.2. Find the velocity, speed, and acceleration of a particle whose path is

$$\mathbf{r}(t) = t^2\mathbf{i} + (t + 2)\mathbf{j} + 3t\mathbf{k}.$$

25.1 Components of the Acceleration Vector

Theorem 25.3. The acceleration vector $\mathbf{a}(t)$ of an object moving along a curve traced out by a twice-differentiable function $\mathbf{r}(t)$ lies in the plane formed by the _____ and the _____ to C . Furthermore,

The coefficients of $\mathbf{T}(t)$ and $\mathbf{N}(t)$ are referred to as the _____ and the _____ respectively.

Problem Set 25.4. A particle moves in a path defined by the vector-valued function $\mathbf{r}(t) = t^2\mathbf{i} + (2t - 3)\mathbf{j} + (3t^2 - 3t)\mathbf{k}$, where t measures time in seconds and distance is measured in feet. Find a_T and a_N .