



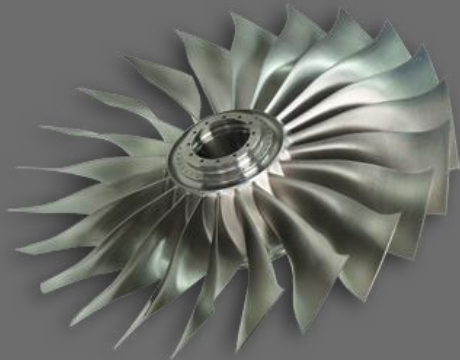
WPI

Automated Tool Prep/Crib & Tool Tracking

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General Electric Aviation (GE)



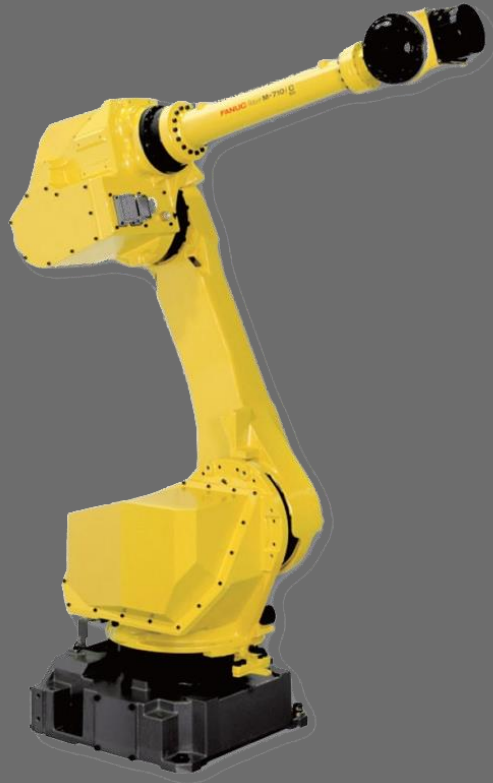
- Create bladed disks
- Use CNC mills to machine
- Workers have to manually change end mills

The Idea

GE has come to WPI with three different objectives that were combined into this project:

- Replace end mills in tool holders and store them (prep)
- Give out new tool holder and end mill combo, an assembly, to a worker when needed (crib)
- Ability to track tool holders (not covered here)

Hardware Provided



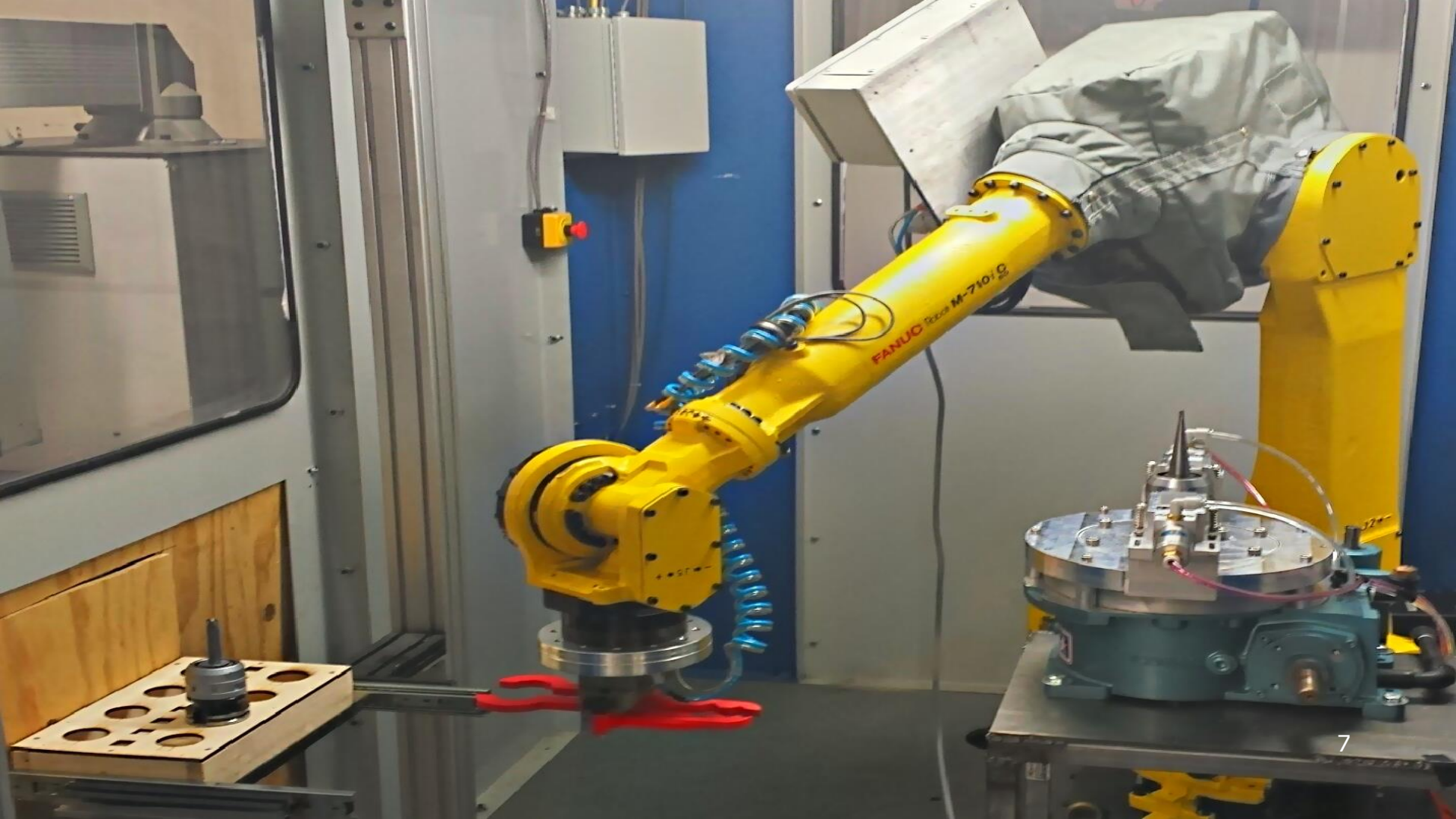
The Work Cell



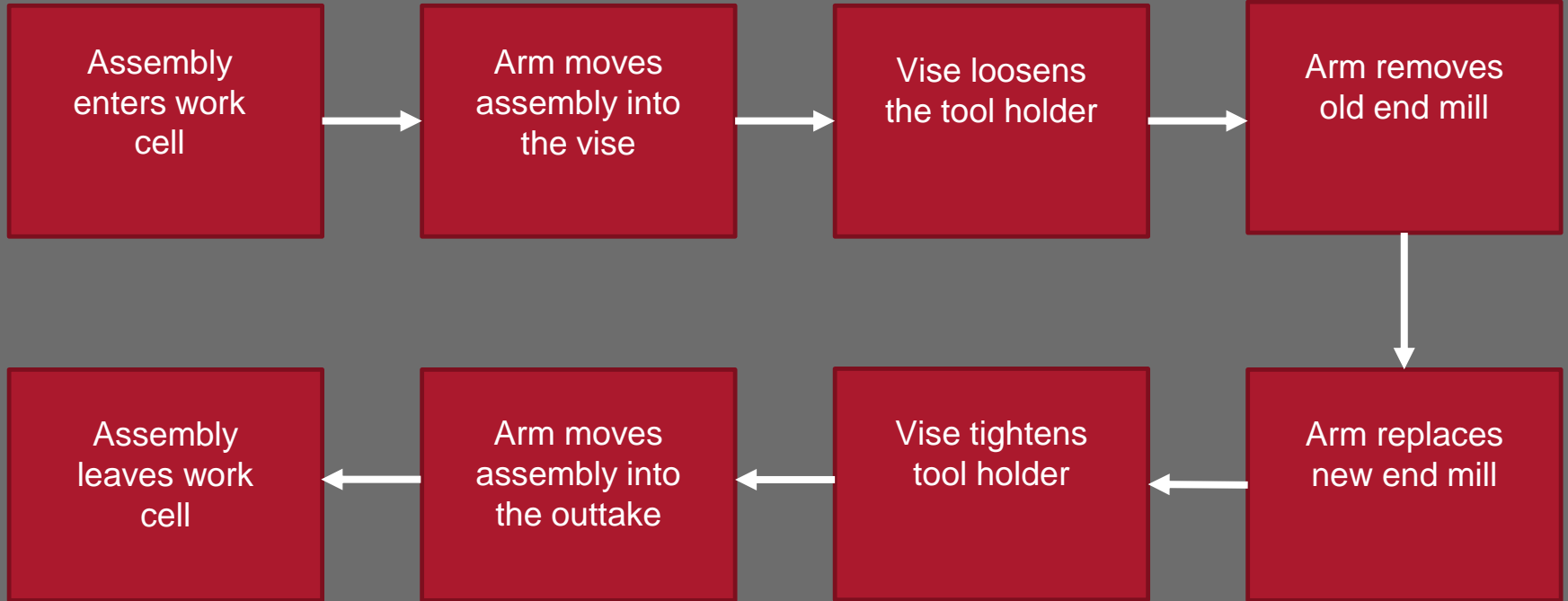
- Made by ACT
- Currently on loan
- Located in WB

Goals

- Develop a process for changing an end mill
- Replace 1 end mill within 1 tool holder
- End mill placed at desired length within a $\pm 0.05''$ tolerance
- 10% acceptable failure rate
- Present said assembly to a worker



The Process

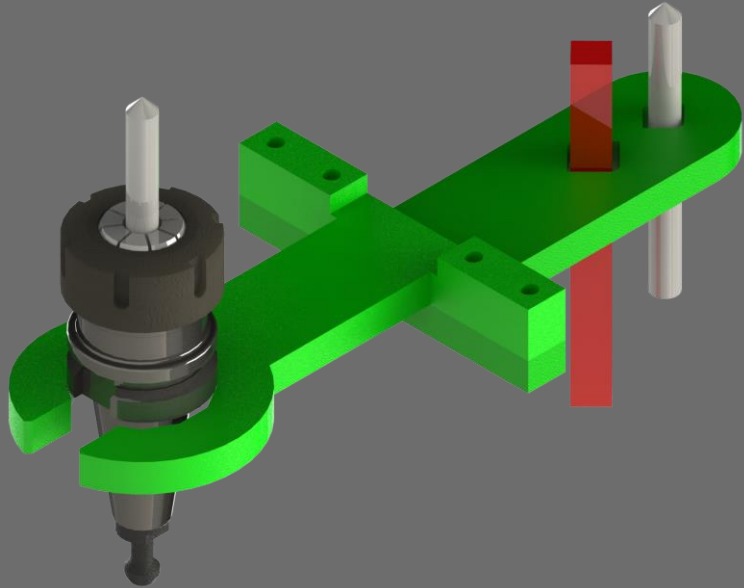


Intake & Outtake - Prep & Crib



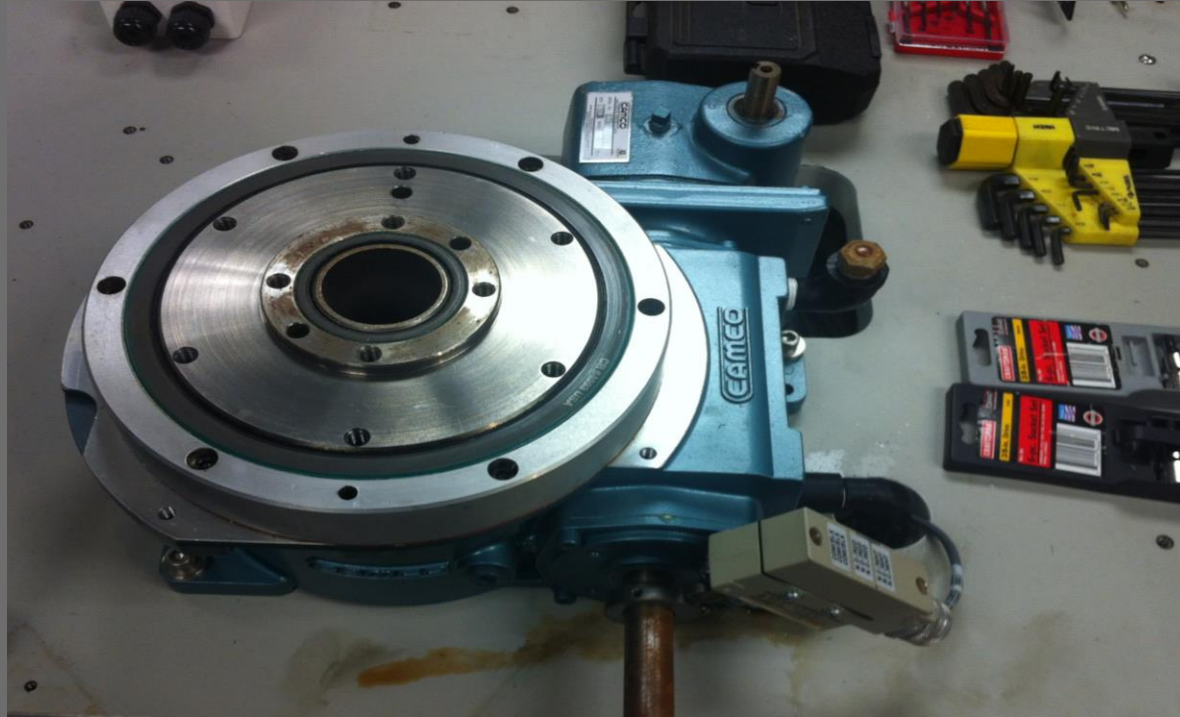
- Accepts assemblies along with new end mills
- Pull out of cell to load up
- Outputs new assemblies

Gripper



- Able to manipulate end mills and tool holders
- Attached to parallel jaw gripper

Indexing Table

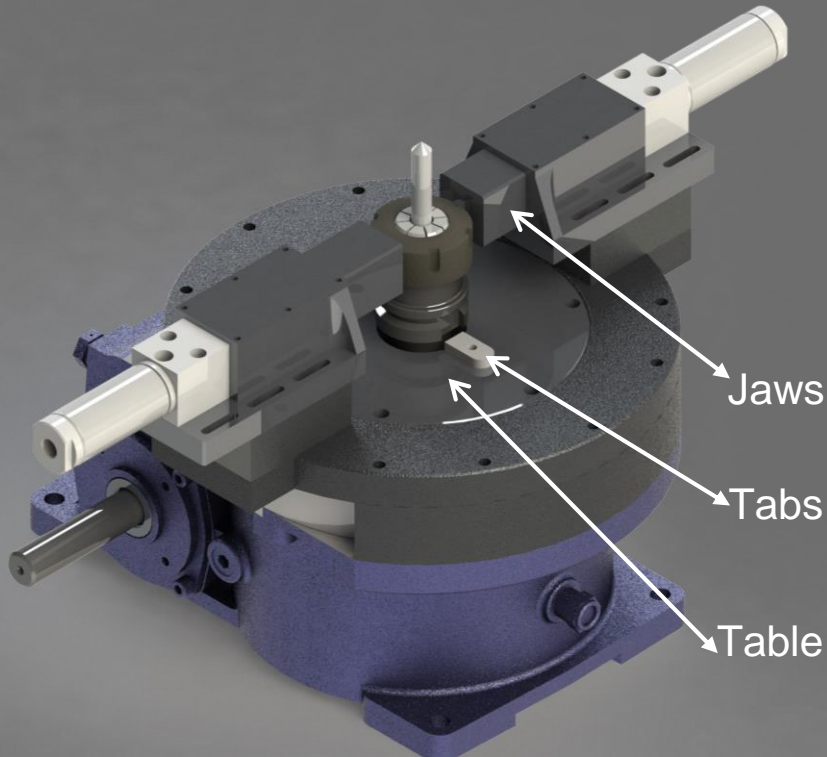


Vise Electronics

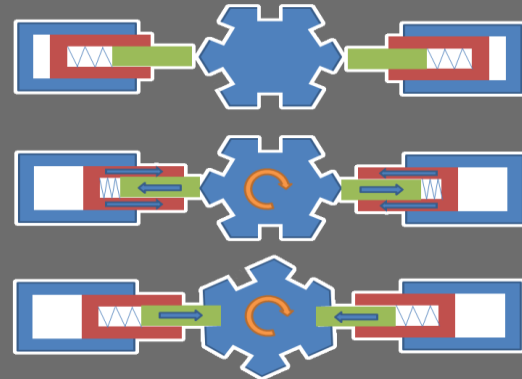
- Motor controller was used to drive the vise
- 3 relays were wired to interface the arm electronics to the controller

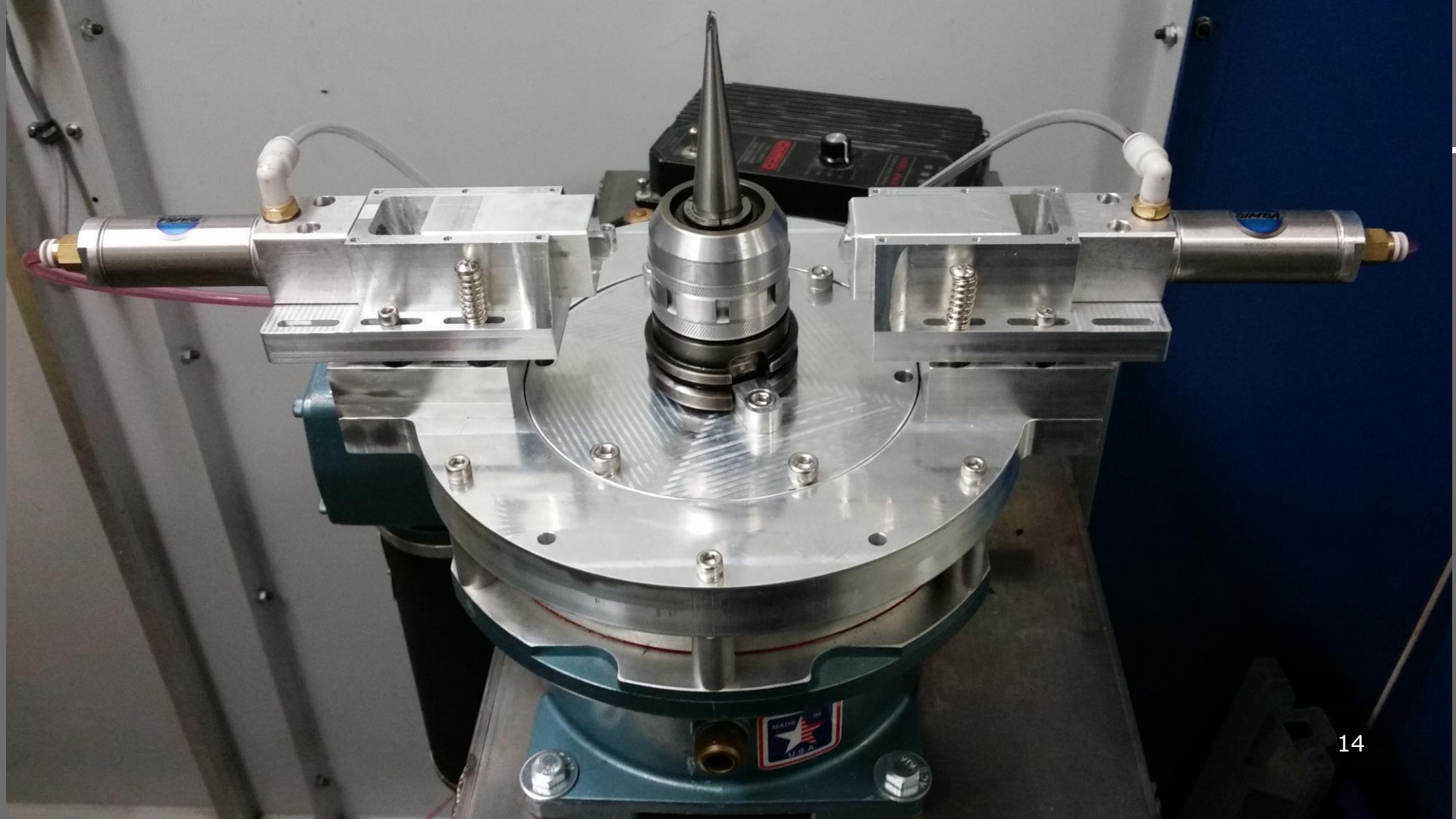


Vise - Tool Prep



- Able to lock in tool holder
- Jaws hold chuck in place while motor spins





Programming

- Arm was moved using the Teach Pendant
- Points were recorded
- Fine adjustments were made to the points



Automatic Tool Changing/Crib

Summary of goals accomplished

- Process was developed
- Able to replace 1 end mill in 1 tool holder
- Due to gripper inconsistencies, length tolerance goal was not met
- Intake and outtake system functions well

Questions?





GRIPPER PIC
